

# **Research Status and Development Trend** of Rice and Wheat Mechanized Harvesting

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# **Overview of rice and wheat Production Mechanization in China**

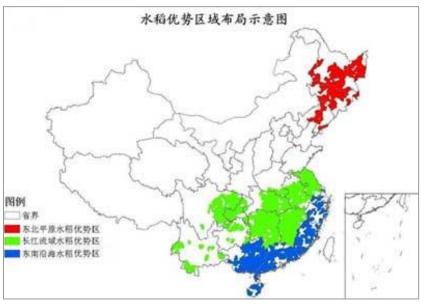
## **Rice planting situation in China**

Rice is the third largest food crop and about 50% of the world take it as main food.

# In China

- rice planting area : 74 million acres
- total yield exceeds 200 million tons
- Three major rice planting areas
  - The Northeast plain
  - Yangtze river basin
  - Southeast Coast

#### **Rice planting distribution in China**



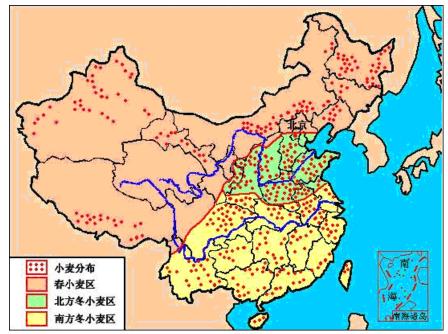
## Wheat planting situation in China

Wheat is the second food crop in China

planting area : 24 million acres

Five major wheat planting areas

- Huanghai
- Middle and lower reaches of the Yangtze River
- Southwest
- Southeast
- Northeast



#### Wheat planting distribution in China

## Machinery system of rice and wheat

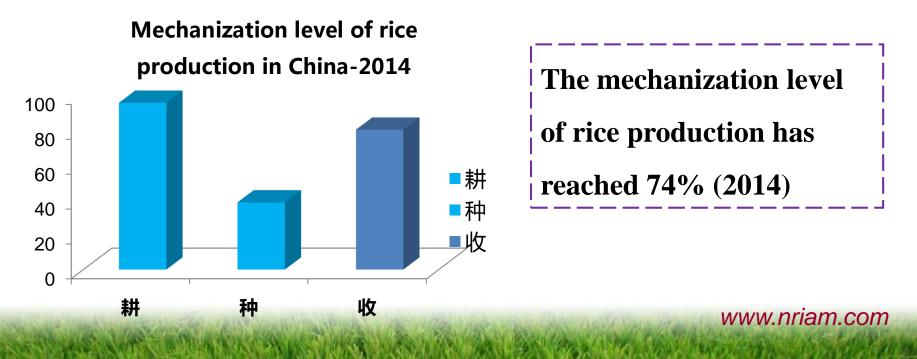
Rice and wheat machinery system refers to the machines and tools involved in the whole process from ploughing, sowing and harvest.

 According to different planting methods, direct seeding machinery or seedling/transplanting machinery is selected.

Harvester is relatively mature technology, including full-feed and semi-feed combine harvesters, as well as segmentation harvesting.

# **Mechanization level of rice production in China**

Mechanization level of rice production in China-2014 (%)				
Ploughing	Sowing	Harvest		
95.57	38.53	80.15		



## **Mechanization level of wheat production in China**

- ◆ The mechanization level of wheat production has reached 94%
- ◆ Wheat is the most mechanized crop in China

## Increase of wheat production Mechanization level from 2006 to 2014

	Tillage (%)	Sowing (%)	Harvesting (%)	Comprehensive (%)
2006	80.21	78.98	78.32	79.27
2014	≈100	86.98	95.08	94.6
Annual growth rate	2.47	1	2.09	1.92

# Key technologies and equipment of rice harvest

## The main form and performance of harvester

## Harvesting method:

#### Two-stage harvester, combine harvester

Combine harvester:

Head-feeding combine harvester, Full-feeding combine harvester



Two-stage harvester

Head-feeding combine harvester

Full-feeding combine harvester

## **Two-stage harvesting**



## **Head-feeding rice combine harvester**



2 rows (0.9m)



4rows (1.5m)



5 rows (1.8m)



6 rows (2.0m)

## **Full-feeding rice combine harvester**



#### Crawler rice combine (working width 2.0m-3.2m)



Wheeled rice combine (working with3.0m-6.2m)

# Key technologies and equipment of rice harvest

Rice and wheat generally use the same combine harvester The main working parts of combine harvester including Header Thresher and separation device **Cleaning device Straw chopper device** Work process video 1: LEXION 600 Crop Flow Gutfluss – 2013 • advanced technologies video 2: 2016 John Deere S-Series Combines

## **Advanced technology of header**

The function of the header is to cut the crop and transport the crop to the threshing device. It consists of reels, cutters, dividers, conveyors, etc.



Video 3: 600 Series Flex Draper Platform

## **Advanced technology of header**



#### Header height profile



hydraulic drive



#### Adjustable floor length



#### Slope adjustment

video 4: VARI O 930-500 - 2016

## **Advanced technology of header**

#### Flexible header



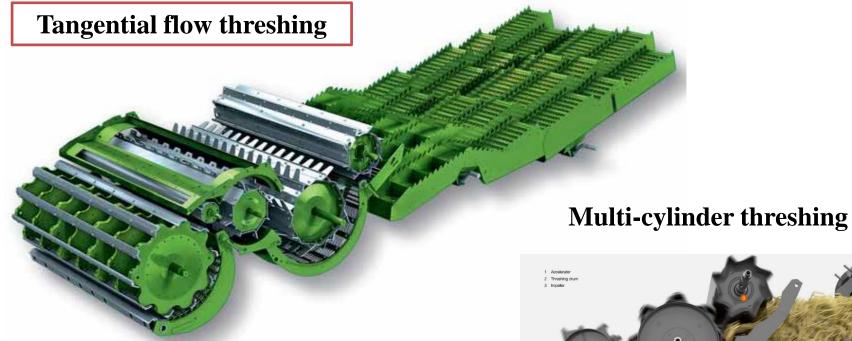
video 5: John Deere 600FD HydraFlex<sup>TM</sup> in Action

## **Threshing device**

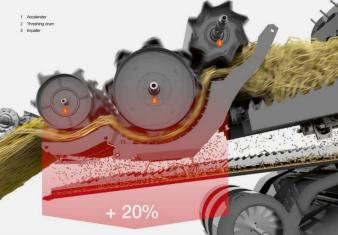
The combine threshing unit/system is the most important assembly from the point of view of working processes and the power requirement

video 6 : Threshing and Separating



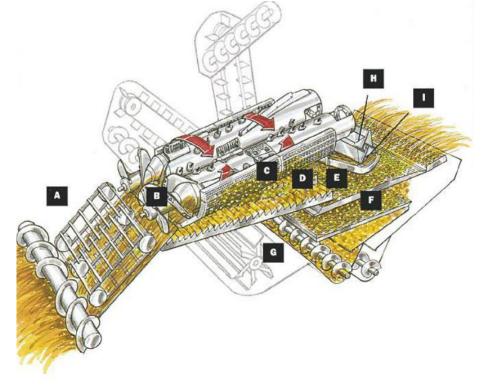


#### **Video 7:** Combine Harvesting Animation (MCS)



## **D** Purpose: Improve threshing efficiency

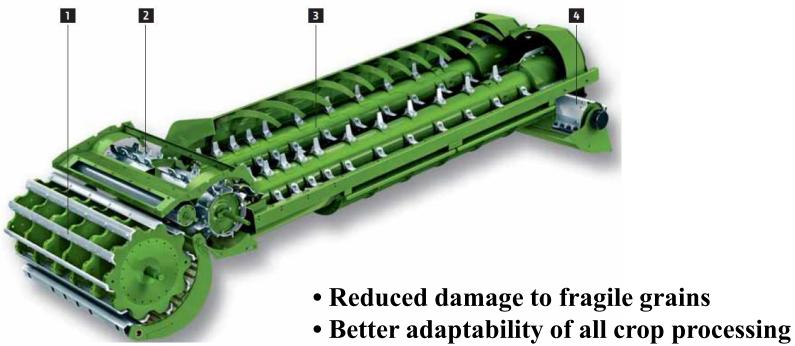




### **Double roller threshing**

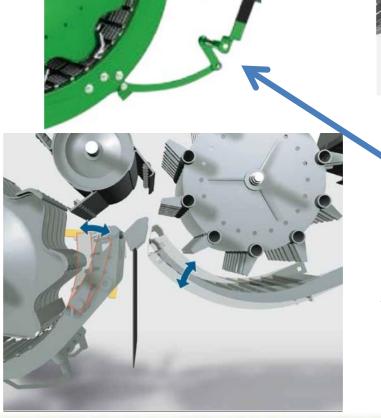
Video 8 CTS System

### **Tangential-longitudinal-axial**



• Low level of grain losses

#### Video 9: CLAAS TUCANO 500 hibrid cséplőrendszer





**Concave adjuster** 

Video 10: John Deere T670 Combine -Concave Booster Bar

The *cleaning shoe*, necessary to both conventional and rotary combines, is usually composed of a receiving element (preparation floor), a grain pan, a chaffer, a sieve, and a blower system



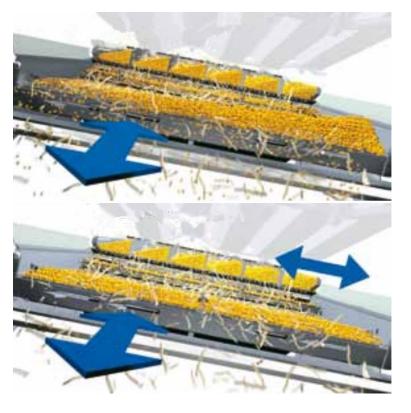
## ◆Self-balancing sieve







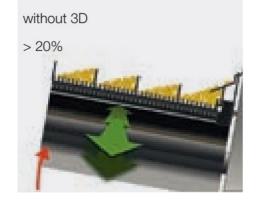
## ♦ 3D cleaning technology



### double-sided vibration mechanism



with 3D > 20%

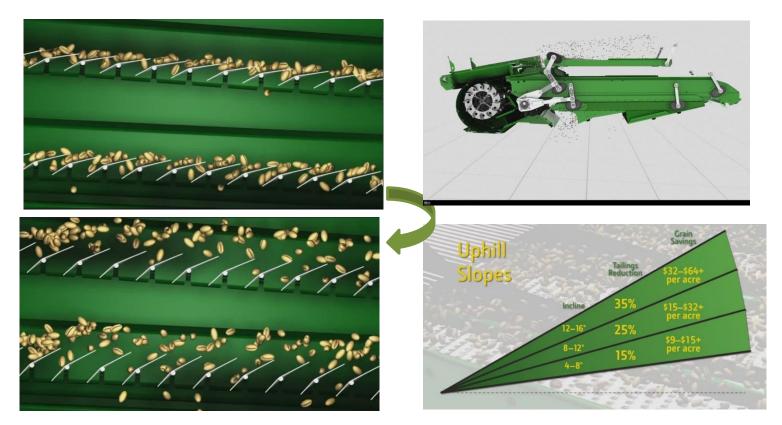


#### Video 11: CLAAS 3D Sieve

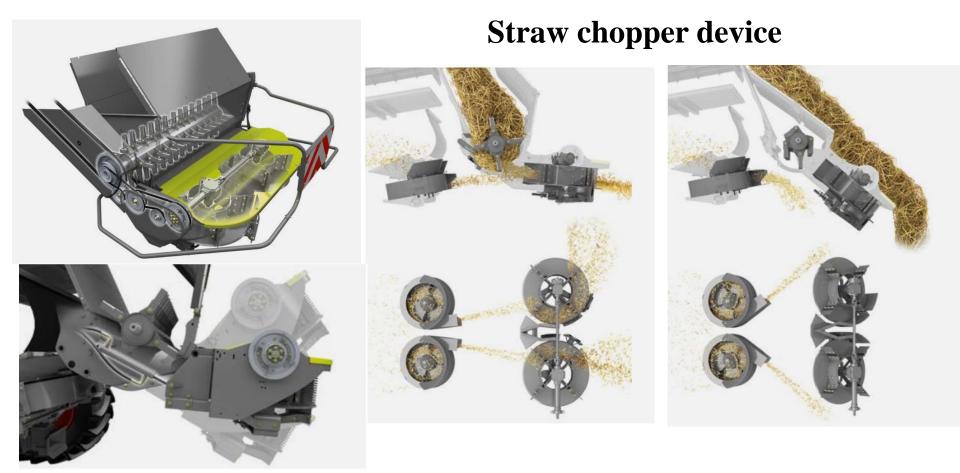
#### ◆4D cleaning technology



#### Screen opening automatic adjustment technology



#### Video 13: Cleaning Shoe Video 14: TUCANO cleaning system - 2016



#### Video 15: CLAAS LEXION - Straw Management 2014 Video 16: CLAAS LEXION SPECIAL CUT - 2016 – en

## **Development trend of combine harvester**

## **Development trend of combine harvester**

Large and<br/>efficientThe power of combine harvesters has<br/>reached more than 770 horsepower. The<br/>main model is about 300 horsepower, with<br/>the maximum width of 24 meters, and 9-12<br/>meters generally.

**Large feed:** John Deere 8kg/s

**Large cutting width Header:** CASE 25 meters

High-efficiency threshing cleaning device



**CLAAS** harvester with a cutting width of 9 meters







## **Development trend of combine harvester**

# Intelligent

computer, automatic control and information technology

www.nriam.com

(1) Combine Harvester Performance Detection System

The system detects the whole harvesting process including the cutting, feeding, threshing and cleaning Device of the combine harvester

- cutter vibration frequency;
- reel speed;
- torque and speed of the threshing roller;
- fan speed and vibration frequency of the vibrating screen.
- +engine speed and operation speed of the combine harvester.

# Intelligent

(2) Combine Harvester Electrical Power-on Self-inspection System

The automatic fault diagnosis of the electrical system can help the combine harvester operator to identify the fault and handle it in time.

(3) Combine Harvester Yield Monitoring System

When the intelligent yield monitoring system is in operation, a group of sensors measure the grain quality or flow per unit time, grain moisture content, machine forward speed, draper platform height, and lifting speed of the grain hoist in real time and transmit digital or analog signals to the control display terminal at the same time to calculate grain yield per unit area.

(4) Measurement of the Entrainment Loss in Combine Harvester

Traditional detection method: By installing "Force-electricity" sensor at the straw outlet

Image detection method: The grain images on the platform are collected by the CCD image detection regularly and sent to the processor for analysis to finally obtain the entrainment data.

(5) Combine Harvester Threshing Roller Monitoring System

The effect of threshing has a direct impact on the performance of cleaning and separation devices

#### (6) Combine Harvester Draper Platform Monitoring System

Digital camera is used to capture images, identify lodged crop automatically and control the height of the harvester draper platform according to the lodging height;

The reel speed is controlled automatically.

#### (7) Measurement of Combine Harvester Cleaning Loss

The amount of grain is detected through the different impact signals of grain and impurities on the sensor.

#### (8) Combine Harvester Drive System

Combine harvester will develop towards electric and hydraulic drive in the future.





Multiple electronic display screens in the cab to keep track of the machine working and operating status at any time



**Convenient one-lever operating system** 



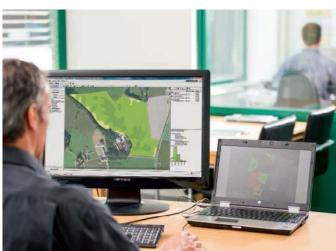


**One-lever operating system** 

#### Management system -Yield map



Automatic navigation system







Threshing roller protection device, overload protection device



Accurate cutting height of John Deere Combine Harvester

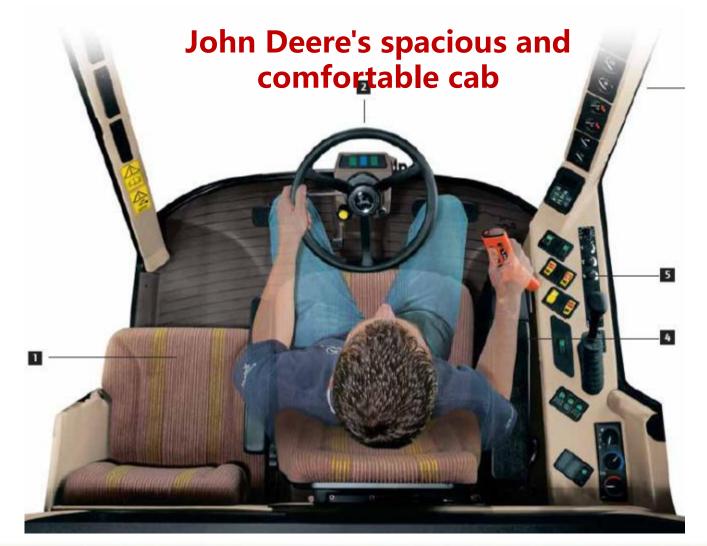
### **Development trend of combine harvester**

Comfortable

Equipped with closed, soundproof, shock-absorbing, and environmental parameter adjustable cab, where the driver can know the position, walking route, working state and operation quality of the harvester through the screen in real time, which has greatly improved operator's operating conditions and reduced the degree of fatigue.



### Comfortable



### **Development trend of combine harvester**

UniversalModular design technology is widely used in<br/>modern combine harvesters. Firstly, the chassis is<br/>designed as a platform with high universality. The<br/>corresponding draper platform is selected<br/>according to the characteristics of the harvested<br/>crop. The threshing and cleaning devices meet the<br/>requirements of different crops generally through<br/>adjusting parameters.

# Universal

#### CLAAS Harvester implements harvesting of a variety of crops through different draper platforms and detached parts



**Rape combine harvester** 



**Rice harvester** 



Soybean harvester



**Corn harvester** 



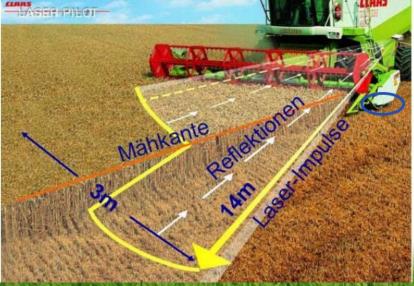
**Pickup machine** 

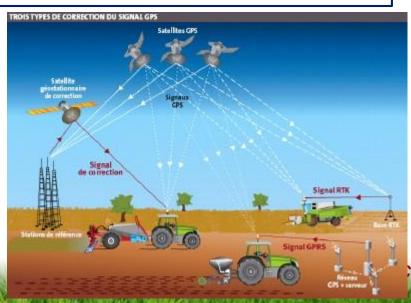


**Grass harvester** 

# **Automatic navigation**

Harvesting according to the optimized path
 Reduce the area of duplicated areas and missing areas
 Improve the quality and efficiency of agricultural machinery in the field
 Reduce the labor intensity of the driver
 remote control and Agricultural Machine Network





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### **Automatic navigation**

Based on Navigation positioning system
≻Crop growth and yield detection
≻Multi-machine cooperative navigation technology
>Obstacle detection and Active obstacle avoidance



